AKAS®-3PM, AKAS®-3PF

# **Operating Instructions** short

translation



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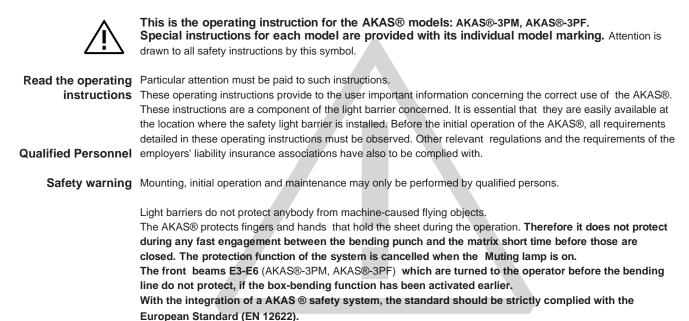
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**CONTENTS: Safety Instructions** Application Instruction for use Mechanical data **Electrical connection** 

### Please observe always



Protection circuits and Emergency can only stop the opening movement when the movement is interupted with the RXOK outputs.

!!! If either test A or B fails, the machine must not be used until the problem is resolved !!!

A-Test: putting into operation

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The B-Test must be done for safety reasons each 5 times on the left end and on the right end of the upper tool.

The press brake must be equipped completely with the heaviest upper tool.

The setting must be done in a way that the following test will be passed:

Start of the closing movement from the maximum top dead centre (T.D.C)

B-Test: daily check (at least every 24 hours)

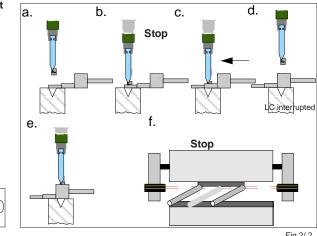
At the beginning of each shift and after each change of tools, the AKAS® press brakes protection must be checked as follows (see also EN 12622.2002):

Test must be carried out at both left and right ends of the bending punch. The punch must not touch the step-shaped test rod.



a.) Place the test piece in position "10" on the lower tool. Select the box bending function if you use a system of the AKAS®3... product family. Now start the close down movement.

- b.) The press brake stops.
- c.) The test piece must be placed in position "15" under the upper tool. In this position ("15") the test piece may not touch the upper tool.
- d.) Drive up the press brake. Place the the test piece in position "35" on the lower tool. Select the normal bending function if you use a system of the AKAS®3... product family. Now start the close down movement.
- e.) The press brake must be stopped in a way that the test piece ("35") may not touch the upper tool.
- f.) Turn on the sender (adjustment keyswitch to ON position) and move the test piece ("14") along the tip of the upper tool. The adjustment а controll LED P1 on the AKAS® receiver has to remain ON during the test.



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# Prerequisites for using the press brake protection AKAS® 2.1

1. Use only tools with the same height in the same fixing on the press. All utilized tools must have one common bending line.

2. Stoppers, which are mounted at the matrix, lead to a premature switching-off of the downward movement.

3. The maximum allowable overrun traverse of the machine: 11mm / AKAS®-3P...

The press must have an automated overrun traverse control for the first stroke. If not, it can be realised by the AKAS®-3PF and a cam controller or by the Fiessler AMS-system. Before the initial start-up, the overrun traverse must be checked either by using the test rod (see page 9) or by using an Overrun Traverse measuring device. (upon custo-mer's request, Fiessler Elektronik will perform the Overrun Traverse Measuring on the customer's machine.) If one results of 10 consecutive measurements is larger than 11mm / AKAS®-3..., the fast speed must be reduced.

4. Due to the missing sychronization during fast speed, AKAS® cannot be used for two machines aligned in parallel (e.g. "tandem press brake").

5. Muting of AKAS.

During the slowspeed closing movent the control system of the machine must send the mute signal to the AKAS receiver. Please refer page 15 how to setup the correct blanking / mute point values. The control system of the machine must reliably guarantee, according to safety category 4, that from this point the stroke speed is <= 10mm / s.

5.1 **Bending boxes with AKAS** If the "boxbending" mode of AKAS is activated the blanking and the muting signal must be activated before the receiver element E2 (for Details see page 12) is interrupted. Please refer page 15 columns "boxmode" how to setup the correct blanking / mute point values for boxbending mode.

5.2 **Bending flat sheets with AKAS** Before the blanking signal is sent to the AKAS receiver any of the receiver elements E1 and E3 – E6 must not be interrupted by the sheet or the lateral die cover (for Details see on page 10) But the receiver element E2 must be interrupted by the sheet or the lateral die cover.

The blanking signal can be a output signal from the machine NC. The closing stroke can continue in high speed until the mute point is reached.

6. The protection of a pressbrake by the AKAS® does not permit bending in the bottom of a box inside the box in fast speed.

7. The AKAS® does not protect:

-if the machine is only run in the work speed, or AKAS will be interrupted during fast speed and the stroke will be continued in work speed

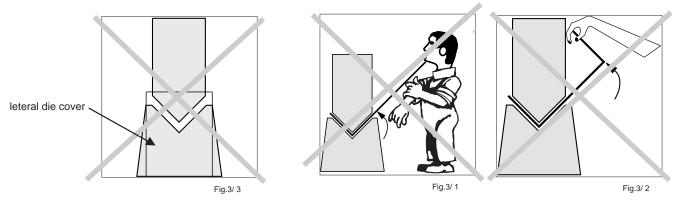
-if the overrun traverse of the press brake is too long

-from squeezing during the bending operation

-if the mutinglamp is constantly on

- if the lateral stencil cover is higher than the top of the die ans the blanking si-

gnal (SP) is set to this wronh position of the leteral die cover. See pic 6/3 together with a wrong SP setting



8. The hazardous state of the machine must be terminated by the sensor function.

9. The safety level (class 4) of the accident preventing light barrier should at least correspond to the safety level of the control system of the machine.

10. Laser beams may be deviated due to air currents, this may cause unwanted and unforeseen machine stops. Therefore the machine must be erected at a place free of air currents.



# Prerequisites for using the press brake protection AKAS® 2.1

Acceptance Acceptance test: the installation acceptance test and inspections should be carried out by a competent person in possession of all the information supplied by the manufacturer of the machine and the ESPE.

Upon customer's request, Fiessler Elektronik will perform the initial acceptance as well as the annual test. Additionally, customer training seminars on how to execute annual tests will be conducted at regular intervals.

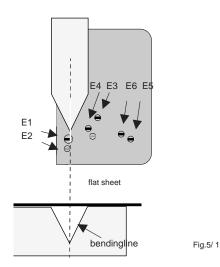
Annual Inspection The machine owner must make sure that a competent person is assigned to check the light barrier annually. This person can be an employee either from the light-barrier manufacturer or from the operator's staff. The annual test shall be executed according to the inspection sheet on pae 49.

FIESSLER	Description and fields of application for the equipment 3
ELEKTRONIK	Function description during bending of flat sheet metal 3.3
bending of flat sheet metal	The V opening of the die must be covered with the lateral die cover. This is necessary because The receiver element E2 must be interrupted before the SP signal ( blanking signal ) is activated. The SP signal must be active before any of the receiver elements E1 or E3 – E6 is interrupted by the sheet or the lateral die cover. The machine can still move in high speed for a maximum of 400ms. After this time the machine must move in slowspeed ( <= 10mm/s ).
stroke start	<ul> <li>-If the SP signal is not active all receiver elements E1 – E6 must be free. During the following closing stroke only E1 u E3 – E6 must be free.</li> <li>-If the SP signal is active the receiver element E2 must be interrupted. Attention, if SP is active but E2 is free, clos stroke is not possible (e.g. lateral die cover is missing or not in correct position)</li> <li>-If the SP signal is active and at least receiver element E2 is interrupted, AKAS will turn off the SGA output (highspeed enable). Only a slowspeed stroke is allowed now.</li> <li>-If the SP signal is not active and at least one of the receiver elements E1 or E3-E6 is interrupted (E2 does not mat now) it is possible to start a slowspeed stroke by pressing the footpedal two times. (SGA will turn off. E.g. for a bend inside a closed box)</li> </ul>
fast speed	<ul> <li>-If the SP signal is not activated the receiver elements E1 and E3-E6 must be free.</li> <li>-If receiver element E2 is already interrupted and the SP signal is just activated, the receiver elements E3 and E must stay free for at least 27ms. (Important: E2 must be interrupted before SP is activated)</li> <li>-If receiver element E2 is already interrupted and SP will be activated, the machine can continue to move in high speed for up to 400ms. Before the 400ms are exceeded the machine must change to slowspeed. (Muting will or be activated in slowspeed)</li> </ul>
Principle of function	1. Release the closing movement by activating the foot pedal. Receiver E1 to E6 are activated

1.Release the closing movement by activating the foot pedal. Receiver E1 to E6 are activated.

2. Press brake closes in fast speed (> 10mm/s)

Receiver element E2 are deactivated, E1,E3 bis E6 activated (protection)



**3.** Position for AKAS blanking reached (SP signal is changing from SP = 0 to SP = 1): The receiver elements E1, E5 and E6 will be muted. E4 will stay active for about 27ms (max allowed travel distance 4mm). E3 will stay active.

**4.** After reaching the change-over point from fast speed to **slow speed (= 10 mm/s)**: (Distance between punch and sheet 0-6mm depending on the stopping distance of the machine) Receiver element E3 will be muted, so the complete AKAS receiver is muted now.

**5.** All receiver elements are muted and the muting lamp is on. The bending procedure is finished. (The fast speed mode and the slow speed mode are limited of about 2 min.)

bending of flat sheet metal

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# Function description during bending of flat sheet metal 3.3

Advice The beams of the AKAS® must be located at a certain distance to the bending punch. (See chapter 5.2 Overrun Traverse Measurement and chapter 5.8 Adjustment of the distance between the AKAS® and the bending punch. Caution! Use only tools with equal overall height within one fixing. Bending of wavy sheet metal Closing movement with interrupted protective field The AKAS® system offers the possibility to execute a closing movement under monitored slow speed even when the protective field is interrupted by a wavy sheet metal. After the interruption of the protective field and the release and reactivation of the foot pedal, the AKAS will deactivate the SGA output when the protective field is interrupted. By this, only slow speed will be enabled by the machine control (NC). AKAS® provides a reaction time of about 200ms for the machine control and then activated the safety switching outputs for the closing movement (OSSDs). The OSSDs remain activated as long as the AKAS® receives a slow speed message to SGS and SGO: by AKAS®...F within the next **70** ms + the selected enhanced tolerance (see page 35/36) by AKAS®...M within the next 170 ms (A tolerance enhancement is possible only with the AKAS®...F systems).

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#### Function description during bending of boxes 3.4

Fig.7/ 1

box bending

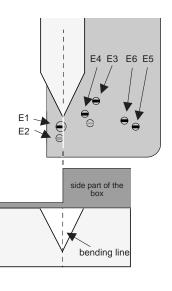
see diagram page 56

Function principle 1. "Box Bending" is activated by the box bending button. The signal at the box bending input KAST must be high (+24V) for at least 100 ms and after that low (0V) for at least 100 ms.

(The box bending function can be canceled by twice activating the box bending button again)

2. AKAS® confirms the selection of the box bending by activating the output HUSP and the LED box-bending

- HUSP output active: The speed change point (fast -> slow) must be a bigger value (refer table 15/1) The receiver elements E3 - E6 are muted, E1 and E2 are active.



3. Release the closing movement by activating the foot pedal. The press closes in fast speed (> 10mm/s).

4. After reaching the change-over point from fast speed to slow speed (= 10 mm/s) : E2 is deactivated, E1 remains activated for 0,5s (5mm) more (=protection)

5. All Receiver elements are muted and the muting lamp is on. The bending procedure is finished. (The fast speed mode and the slow speed mode are limited of about 2 min.)

6. After the bending procedure the box bending functiuon is cancelled.

Bending of the box bottom

### Closing movement with interrupted protective field

lead to the switching off of the bending process!

The AKAS® system offers the possibility to execute a closing movement under monitored slow speed even when the protective field is interrupted.

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by AKAS®...F within the next 70 ms + the selected enhanced tolerance (see page 36/37)

by AKAS®...M within the next 170 ms (A tolderance enhancement is possible only with the AKAS®...F systems).

In the case of bending of very small pieces, which must be guided by the fingers, the box-bending function

must be selected. Otherwise, the fingers would interrupt E3, E4, E5, E6 (AKAS®-3P M/-F) which would

With activated box-bending function, a finger which is placed next to the slog on a large matrix, is not

Bending of very small pieces

detected!!

After the interruption of the protective field and the release and reactivation of the foot pedal, the AKAS will deac-

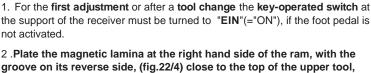
# adjustment directions - after tool change 5.8

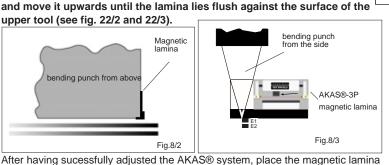
# AKAS®-3P...

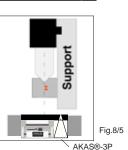
Automatik

AKAS®-3P

magnetic lamina reverse side.







AKAS®-3P magnetic lamina at the side of the matrix

Bild8/1

tool tip.

Fig.8/4

Groove for the

at the side of the matrix (as shown in fig. 22/5) in order to cover it. It must be attached in a way that its edge is even with the matrix surface.

During the whole operation, the magnetic lamina must remain at the side of the matrix in order to cover it.

3. Now, the operator may choose from 2 different adjustment modes:

# A. Automatic adjustment (Automatic Mode):

By pushing **ONCE** the button "*Automatik*" this adjustment mode is started. The procedure is automatically stopped as soon as the AKAS® system has reached the correct distance beneath the bending punch. The automated adjustment procedure can be interrupted, if - during the downward movement of both the AKAS®-transmitter and the AKAS®-receiver - the *switch* "*Sender auf*" (*=transmitter up*) is activated. (This action will be of help primarily in the case of a large tool being exchanged by a considerably smaller tool.) By doing this, the downward movement of the transmitter and receiver towards the lowest point is prevented or stopped. If the transmitting light beam hits the receiver elements, i.e. the optics of both components are "locked into one another" (focussing), the AKAS® system will adjust itself automatically onto the exchanged tool newly fixed at the ram. If the light beam from the transmitter does not hit the receiver (i.e. the transmitter beams are interrupted by the newly mounted tool), both transmitter and receiver will move downward to the lowest point of the displacing range. When moving upwards again, they are searching the lower edge of the bending punch. The system will automatically adjust itself to the newly installed bending punch.



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You will find these adjustment

pof the receiver support!

directions also on the from plate

adjustment directions

After having carried out this, the key at the **key-operated switch** is turned to "Aus" (=OFF) and the key is removed from its lock.

After having completed the adjustment procedure, the tests (see page 9) must be carried out. If the key of the key-operated switch is removed from its lock, the outputs of the system are free only if the " Automated Mode" has been competely terminated.

#### B. Adjusting by hand (Manual Mode):

By activating the button "**Sender ab**" (=transmitter down) the manual adjustment mode is started. Now the operator must check if either the transmitter beam hits the receiver : - adjustment indicators P do not light up (see **B1**) - or if the transmitter beam does not hit the receiver - adjustment indicators P light up (see **B2**)

B1: (This function is required during the first adjusting of the system) Schematic layout of the AKAS®-II-transmitter and AKAS®-receiver can be carried up-AKAS®-II after a tool changewards or downwards by activating the switch "Sender auf / Senover and of the consecutive Α der ab" (transmitter up / down). This is to verify whether both follow-up of the transmitter and transmitter and receiver are correctly mounted parallel to the benthe receiver. . ding line of the machine. By activating the "Automatik"-button, the operator may start the automated adjusting procedure. B2:(This function is carried out if the transmitter beam does NOT hit the receiver, p.e. if high matrixes are used) в By activating the "Automatik"-button or the "receiver up"-button, the receiver is carried upwards. At the same time, the transmitter can be carried upwards by activating the switch "Sender auf/ab" (=transmitter up/down). As soon as the transmitter beam hits the receiver again - adjustment indicators P are out at the receiver-, the adjusting procedure can be terminated as described in the

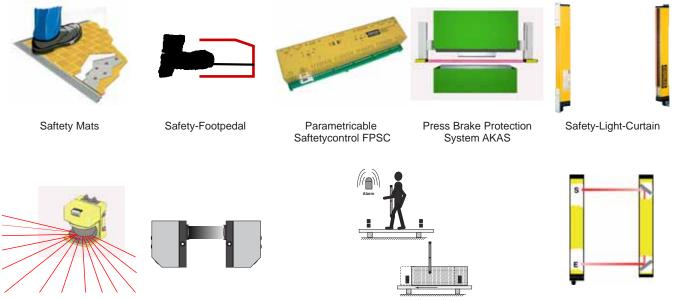
Bild8/5



If the key of the key-operated switch is removed from its lock, the outputs of the system are free only if the "Automated Mode" has been competely terminated. The key switch must not be turned, if the foot pedal is activated. The key must be kept under the control of a responsible person (set-up man)!

automated adjustment "Automatic Mode" A.).

Inspection Sheet	Inspection of a press brake safeguarded by a press brake protection system AKAS®
Date:	
customer's	Hex schwitch position:
order number:	machine builder
	machine type: Serial no
address: department:	machine control by:
Post Code/City:	machine located at:
	inventory no.:
•	cost centre: type of control:
attending staff:	AKAS® no.
nspecting company:	AMS no:
inspector:	
. Inspection:	
	tenance contract existing
regular inspection	estimate of maintenance contract requested
. Installation:	·
etection range: m	optional swivable holder at: 🔲 transmitter 🔲 receiver
. Visual Inspection of the Insta	Illation
3.1 correct electric connection	3.10 max. work speed: mm/s
3.2 cables damage free	3.11 max. fast speed: mm/s
3.3 strain relief at both sides of	f cable loop 3.12 Overrun traverse of the AKAS® is: mm
	mechanical damages by metal sheet when interrupted during fast speed motion
	ight grid (not too far behind from bending line)
] 3.6 correct position of vertical li	ight grid (distance sufficiently behind the bending line)
3.7 transmitter beams are para	Illel to the ram
3.7 transmitter beams are para 3.8 work speed < 10 mm/s	Ilel to the ram
	Illel to the ram
3.8 work speed < 10 mm/s 3.9 test with test rod passed fter viewing of the electrical diag	grams, the electrical integration of the AKAS® can be accepted as safe according to
3.8 work speed < 10 mm/s 3.9 test with test rod passed fter viewing of the electrical diag	
3.8 work speed < 10 mm/s 3.9 test with test rod passed fter viewing of the electrical diag afety class 4 EN 954T.1, under t	grams, the electrical integration of the AKAS $^{ m e}$ can be accepted as safe according to the condition that the machine control is wired exactly as shown in the said diagrams.
3.8 work speed < 10 mm/s 3.9 test with test rod passed fter viewing of the electrical diag	grams, the electrical integration of the AKAS® can be accepted as safe according to the condition that the machine control is wired exactly as shown in the said diagrams.
3.8 work speed < 10 mm/s 3.9 test with test rod passed (ter viewing of the electrical diag afety class 4 EN 954T.1, under t . Cooperation between the AK	grams, the electrical integration of the AKAS® can be accepted as safe according to the condition that the machine control is wired exactly as shown in the said diagrams.
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<ul> <li>3.8 work speed &lt; 10 mm/s</li> <li>3.9 test with test rod passed</li> <li>after viewing of the electrical diagatety class 4 EN 954T.1, under t</li> <li><b>Cooperation between the AK</b></li> <li>4.1 The stopping of the AKAS®</li> <li>4.2 control elements : OK</li> <li>4.3 closing movement during for</li> </ul>	grams, the electrical integration of the AKAS® can be accepted as safe according to the condition that the machine control is wired exactly as shown in the said diagrams. <b>AS® system and the machine</b> B during the dangerous movement complies with the safety level of safety category 4 oot operated motion with AKAS® only possible when foot pedal remains pressed down
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<ul> <li>3.8 work speed &lt; 10 mm/s</li> <li>3.9 test with test rod passed</li> <li>4.1 The stopping of the AKAS®</li> <li>4.1 The stopping of the AKAS®</li> <li>4.2 control elements : OK</li> <li>4.3 closing movement during for</li> <li>4.4 interruption of the AKAS®</li> <li>4.5 interruption of the AKAS®</li> <li>4.6 operation mode "foot-fast m</li> <li>4.7 AKAS® is switched off in a</li> <li>4.8 Muting signal is given if the</li> <li>4.9 Muting signal from valve point</li> </ul>	grams, the electrical integration of the AKAS® can be accepted as safe according to the condition that the machine control is wired exactly as shown in the said diagrams. <b>AS® system and the machine</b> a during the dangerous movement complies with the safety level of safety category 4 oot operated motion with AKAS® only possible when foot pedal remains pressed down o during fast speed: OK during work speed: OK notion" is possible only when AKAS® is activated all operation modes where AKAS® is not activated a gap above metal sheet corresponds to distance between "lower edge E2 and tool tip+2mn position signal during work stroke or AMS
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<ul> <li>3.8 work speed &lt; 10 mm/s</li> <li>3.9 test with test rod passed</li> <li>4.1 The stopping of the AKAS®</li> <li>4.1 The stopping of the AKAS®</li> <li>4.2 control elements : OK</li> <li>4.3 closing movement during for</li> <li>4.4 interruption of the AKAS®</li> <li>4.5 interruption of the AKAS®</li> <li>4.6 operation mode "foot-fast m</li> <li>4.7 AKAS® is switched off in a</li> <li>4.8 Muting signal is given if the</li> <li>4.9 Muting signal from valve point</li> </ul>	grams, the electrical integration of the AKAS® can be accepted as safe according to the condition that the machine control is wired exactly as shown in the said diagrams. <b>AS® system and the machine</b> <sup>®</sup> during the dangerous movement complies with the safety level of safety category 4 oot operated motion with AKAS® only possible when foot pedal remains pressed down a during fast speed: OK during work speed: OK notion" is possible only when AKAS® is activated all operation modes where AKAS® is not activated a gap above metal sheet corresponds to distance between "lower edge E2 and tool tip+2mn position signal during work stroke or AMS by AKAS®, Safety PLC e.g. <b>FPSC</b> or machine control by machine control
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Proximity Laser Scanner

Single-Safety-Beam

Safety-Light-Grid with muting function

Safety-Light-Grid

# Service

As a special feature for training our customers, Fiessler Elektronik offers one-day safety workshops. Our service team provides you with expert advice and information for the reliable integration of our safety equipment into your machine.

#### HOMOLOGATIONS

In order to ensure and maintain the high quality level of the Fiessler safety products, a quality control security system has been established early. Fiessler Elektronik holds the DIN ISO EN 9001 Certificate and, thanks to the company-owned EMC laboratory, all products must pass a inspection without exception before they leave the company. All safety equipment comply with the applicable national and international standards. Development and Design is made in close cooperation with the German employer's liablility insurance associations. All homologations are obtained only after having passed strict tests by the German surveyor organisation TÜV.

## AWARD OF

### **APPRECIATION**

for exemplary performance in the development of the press brake protection system AKAS. The award was bestowed upon Fiessler Elektronik by the ministry of trade and commerce of the federal state of Baden-Württemberg.





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Fiessler Elektronik has respresentations in all major industrial

